#### COP 4710: Database Systems Spring 2006

#### CHAPTER 10 – INDEXING – Part 2

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Instructo	

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# Static Hashing

- A **bucket** is a unit of storage containing one or more records (a bucket is typically a disk block).
- In a **hash file organization** we obtain the bucket of a record directly from its search-key value using a **hash function**.
- Hash function *h* is a function from the set of all search-key values *K* to the set of all bucket addresses *B*.
- Hash function is used to locate records for access, insertion as well as deletion.
- Records with different search-key values may be mapped to the same bucket; thus entire bucket has to be searched sequentially to locate a record.

# Example of Hash File Organization

Hash file organization of *account* file, using *branch-name* as key (See figure in next slide.)

- There are 10 buckets,
- The binary representation of the *i*th character is assumed to be the integer *i*.
- The hash function returns the sum of the binary representations of the characters modulo 10

- E.g. h(Perryridge) = 5 h(Round Hill) = 3 h(Brighton) = 3

#### **Example of Hash File Organization**

Hash file organization of *account* file, using *branch-name* as key

(see previous slide for details).

Page 4 Mark Llewellyn ©					
				_	
Redwood	700				
		bucket 9			
		11110	Domitowit	000	
Round Hill				600	
Brighton	750		Downtown	500	
		bucket 8			
		A-215	Mianus	700	
		bucket 7	-		
		bucket 6			
		A-218	Perryridge	700	
		A-201	Perryridge	900	
		A-102	Perryridge	400	
	Brighton Round Hill Redwood	Round Hill 350	A-201         A-218         bucket 6         bucket 7         A-215         bucket 8         Brighton       750         Round Hill       350         A-101         A-101         A-101         Brighton       750         Brighton       750         Bucket 8         Brighton       750         Bucket 9       500	A-102PerryridgeA-201PerryridgeA-218PerryridgeIIbucket 6IIbucket 7IA-215MianusIIIIbucket 8Brighton750Round Hill350III <td< td=""></td<>	

# Hash Functions

- Worst has function maps all search-key values to the same bucket; this makes access time proportional to the number of search-key values in the file.
- An ideal hash function is **uniform**, i.e., each bucket is assigned the same number of search-key values from the set of *all* possible values.
- Ideal hash function is **random**, so each bucket will have the same number of records assigned to it irrespective of the *actual distribution* of search-key values in the file.
- Typical hash functions perform computation on the internal binary representation of the search-key.
  - For example, for a string search-key, the binary representations of all the characters in the string could be added and the sum modulo the number of buckets could be returned.

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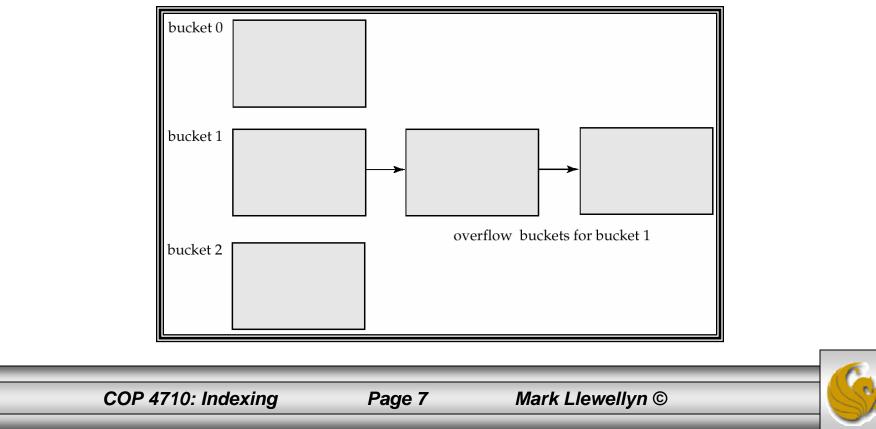
# Handling of Bucket Overflows

- Bucket overflow can occur because of
  - Insufficient buckets
  - Skew in distribution of records. This can occur due to two reasons:
    - multiple records have same search-key value
    - chosen hash function produces non-uniform distribution of key values
- Although the probability of bucket overflow can be reduced, it cannot be eliminated; it is handled by using *overflow buckets*.



## Handling of Bucket Overflows (cont.)

- Overflow chaining the overflow buckets of a given bucket are chained together in a linked list.
- Above scheme is called closed hashing.
  - An alternative, called open hashing, which does not use overflow buckets, is not suitable for database applications.



## Hash Indices

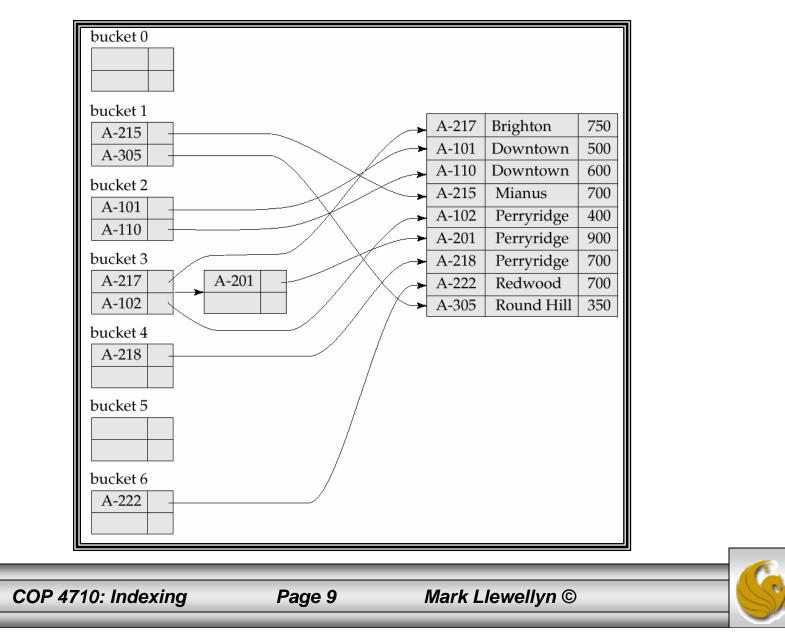
- Hashing can be used not only for file organization, but also for index-structure creation.
- A hash index organizes the search keys, with their associated record pointers, into a hash file structure.
- Strictly speaking, hash indices are always secondary indices
  - if the file itself is organized using hashing, a separate primary hash index on it using the same search-key is unnecessary.
  - However, we use the term hash index to refer to both secondary index structures and hash organized files.

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#### **Example of Hash Index**



# **Deficiencies of Static Hashing**

- In static hashing, function *h* maps search-key values to a fixed set of *B* of bucket addresses.
  - Databases grow with time. If initial number of buckets is too small, performance will degrade due to too much overflows.
  - If file size at some point in the future is anticipated and number of buckets allocated accordingly, significant amount of space will be wasted initially.
  - If database shrinks, again space will be wasted.
  - One option is periodic re-organization of the file with a new hash function, but it is very expensive.
- These problems can be avoided by using techniques that allow the number of buckets to be modified dynamically.

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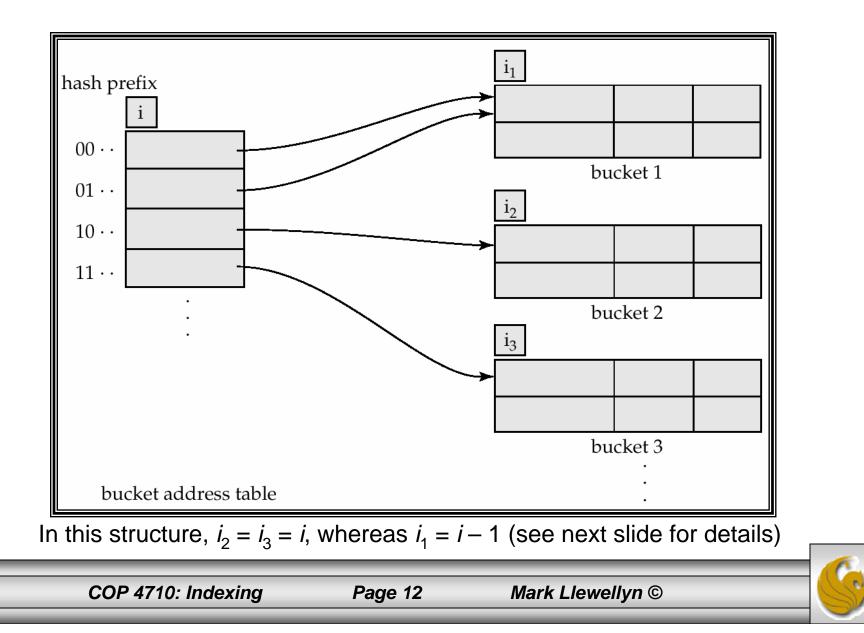
# **Dynamic Hashing**

- Good for database that grows and shrinks in size
- Allows the hash function to be modified dynamically
- **Extendable hashing** one form of dynamic hashing
  - Hash function generates values over a large range typically *b*-bit integers, with b = 32.
  - At any time use only a prefix of the hash function to index into a table of bucket addresses.
  - Let the length of the prefix be *i* bits,  $0 \le i \le 32$ .
  - Bucket address table size =  $2^{i}$ . Initially i = 0
  - Value of i grows and shrinks as the size of the database grows and shrinks.
  - Multiple entries in the bucket address table may point to a bucket.
  - Thus, actual number of buckets is  $< 2^i$ 
    - The number of buckets also changes dynamically due to coalescing and splitting of buckets.

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#### **General Extendable Hash Structure**



#### Use of Extendable Hash Structure

- Each bucket *j* stores a value  $i_j$ ; all the entries that point to the same bucket have the same values on the first  $i_j$  bits.
- To locate the bucket containing search-key  $K_i$ :
  - 1. Compute  $h(K_j) = X$
  - 2. Use the first *i* high order bits of *X* as a displacement into bucket address table, and follow the pointer to appropriate bucket
- To insert a record with search-key value  $K_i$ 
  - follow same procedure as look-up and locate the bucket, say *j*.
  - If there is room in the bucket *j* insert record in the bucket.
  - Else the bucket must be split and insertion re-attempted (next slide.)
    - Overflow buckets used instead in some cases

#### Updates in Extendable Hash Structure

To split a bucket *j* when inserting record with search-key value  $K_j$ :

- If  $i > i_i$  (more than one pointer to bucket *j*)
  - allocate a new bucket z, and set  $i_j$  and  $i_z$  to the old  $i_j$  -+ 1.
  - make the second half of the bucket address table entries pointing to j to point to z
  - remove and reinsert each record in bucket *j*.
  - recompute new bucket for  $K_j$  and insert record in the bucket (further splitting is required if the bucket is still full)
- If  $i = i_j$  (only one pointer to bucket j)
  - increment *i* and double the size of the bucket address table.
  - replace each entry in the table by two entries that point to the same bucket.
  - recompute new bucket address table entry for  $K_j$ Now  $i > i_j$  so use the first case above.

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# Updates in Extendable Hash Structure (cont.)

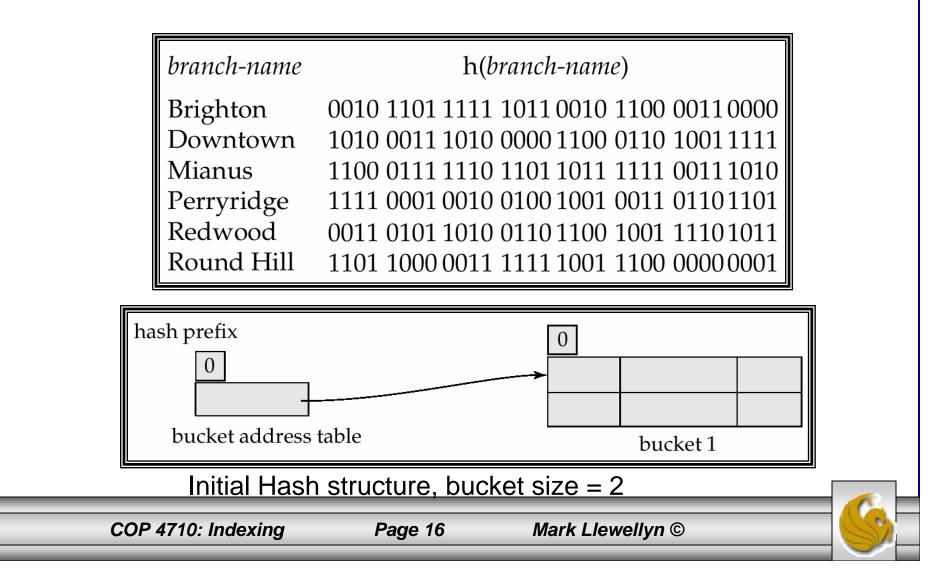
- When inserting a value, if the bucket is full after several splits (that is, *i* reaches some limit *b*) create an overflow bucket instead of splitting bucket entry table further.
- To delete a key value,
  - locate it in its bucket and remove it.
  - The bucket itself can be removed if it becomes empty (with appropriate updates to the bucket address table).
  - Coalescing of buckets can be done (can coalesce only with a "buddy" bucket having same value of  $i_j$  and same  $i_j-1$  prefix, if it is present)
  - Decreasing bucket address table size is also possible
    - Note: decreasing bucket address table size is an expensive operation and should be done only if number of buckets becomes much smaller than the size of the table

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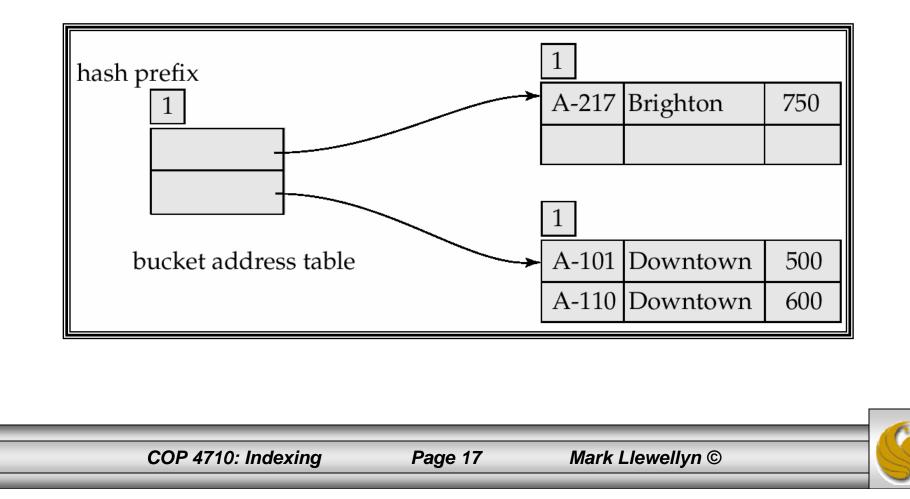
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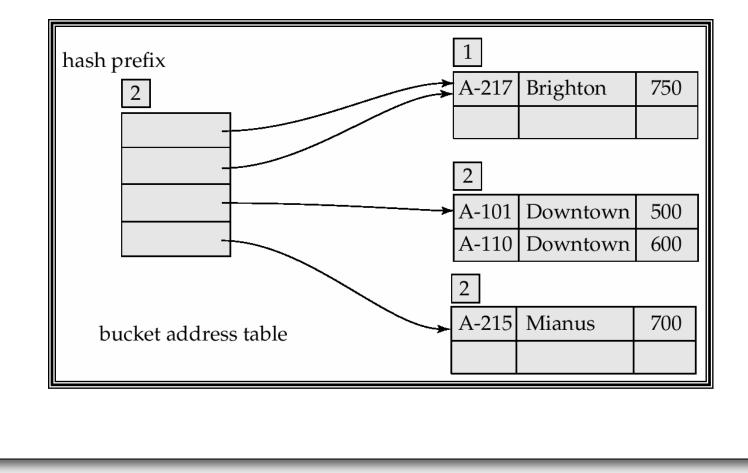
#### Use of Extendable Hash Structure: Example



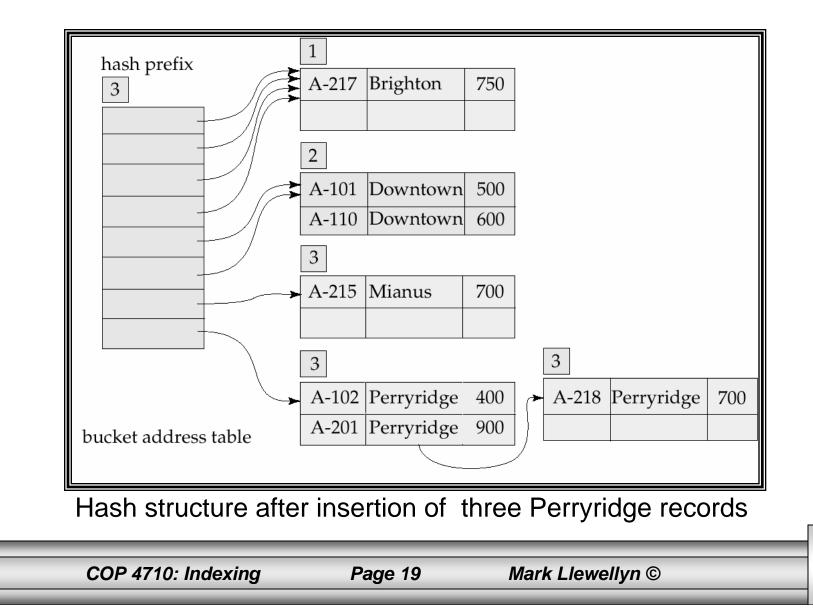
• Hash structure after insertion of one Brighton and two Downtown records



Hash structure after insertion of Mianus record

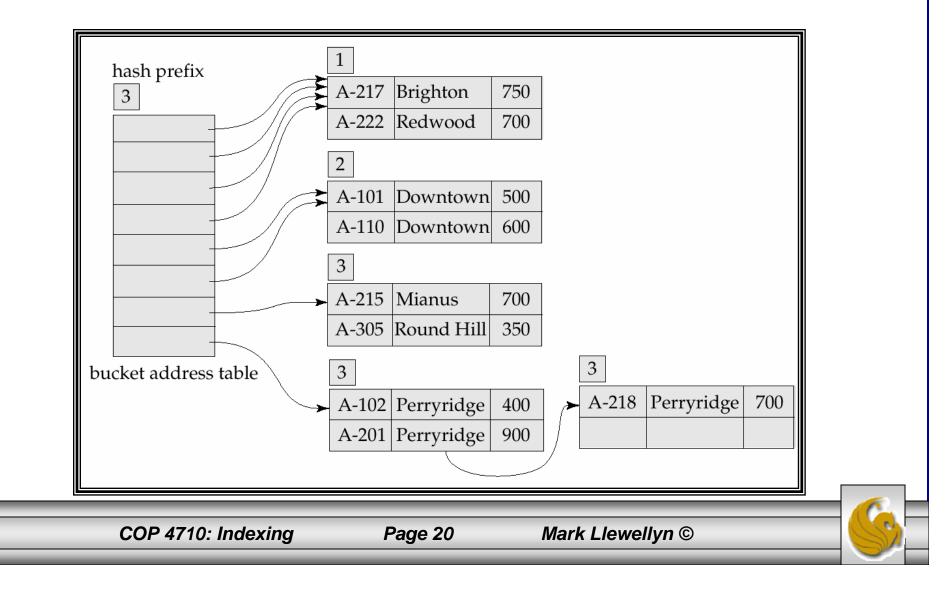








• Hash structure after insertion of Redwood and Round Hill records



#### Extendable Hashing vs. Other Schemes

- Benefits of extendable hashing:
  - Hash performance does not degrade with growth of file
  - Minimal space overhead
- Disadvantages of extendable hashing
  - Extra level of indirection to find desired record
  - Bucket address table may itself become very big (larger than memory)
    - Need a tree structure to locate desired record in the structure!
  - Changing size of bucket address table is an expensive operation
- Linear hashing is an alternative mechanism which avoids these disadvantages at the possible cost of more bucket overflows



#### **Comparison of Ordered Indexing and Hashing**

- Cost of periodic re-organization
- Relative frequency of insertions and deletions
- Is it desirable to optimize average access time at the expense of worst-case access time?
- Expected type of queries:
  - Hashing is generally better at retrieving records having a specified value of the key.
  - If range queries are common, ordered indices are to be preferred

# **Multiple-Key Access**

- Use multiple indices for certain types of queries.
- Example:

select account-number
from account
where branch-name = "Perryridge" and balance = 1000

- Possible strategies for processing query using indices on single attributes:
  - 1. Use index on *branch-name* to find accounts with balances of \$1000; test *branch-name* = "Perryridge".
  - 2. Use index on *balance* to find accounts with balances of \$1000; test *branch-name* = "Perryridge".
  - 3. Use *branch-name* index to find pointers to all records pertaining to the Perryridge branch. Similarly use index on *balance*. Take intersection of both sets of pointers obtained.

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# Indices on Multiple Attributes

- Suppose we have an index on combined search-key(*branch-name*, *balance*).
- With the **where** clause

where *branch-name* = "Perryridge" and *balance* = 1000 the index on the combined search-key will fetch only records that satisfy both conditions.

Using separate indices in less efficient — we may fetch many records (or pointers) that satisfy only one of the conditions.

- Can also efficiently handle
   where *branch-name* "Perryridge" and *balance* < 1000</li>
- But cannot efficiently handle where *branch-name* < "Perryridge" and *balance* = 1000 May fetch many records that satisfy the first but not the second condition.

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